# A Choreographic Authoring System for Character Dance Animation Reflecting a User's Preference

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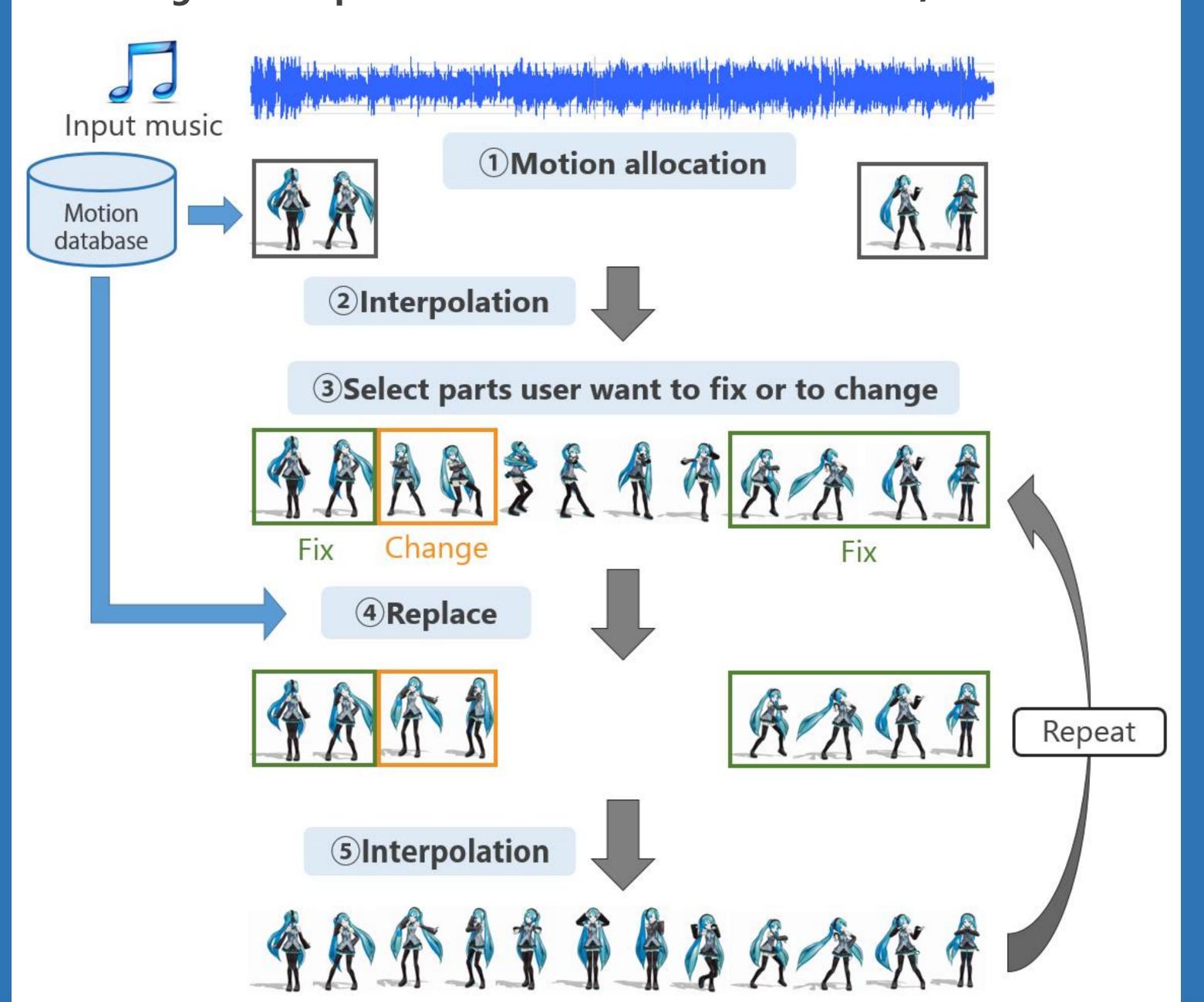
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## Goal

To realize a choreographic authoring system for character animation reflecting a user's preference with less burden for him/her.

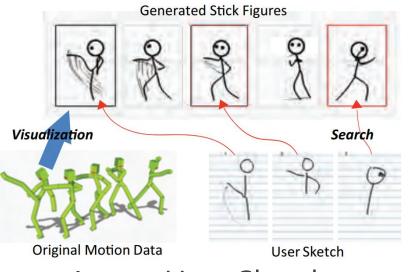


# Introduction

- We focus on two issues:
- 1 How can we enable a user to easily search for his/her preferred motion?
- 2 How can we semi-automatically synthesize a sequence of dance?
- Related work
- 1) Motion retrieval



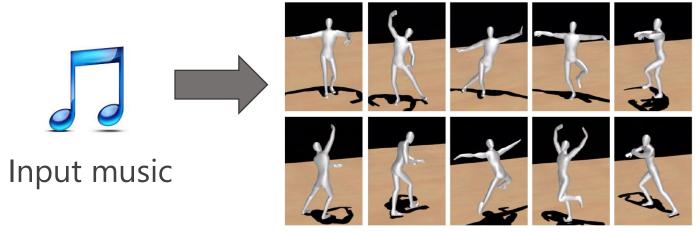
Input: Motion Data
[Michalis et al. SCA2011]



Input: User Sketch
[Choi et al. PG2012]

A large burden is often placed on the user.

2 Dance motion synthesis



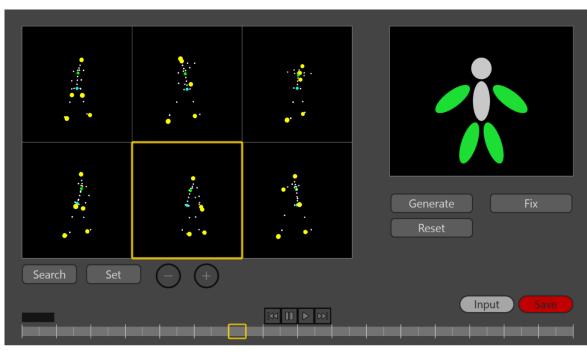
This cannot automatically synthesize a sequence under the constraint condition that the motions touched by the user are fixed.

[Shiratori et al. EG2006]

# Dance Search System

## ◆ Dance search system design

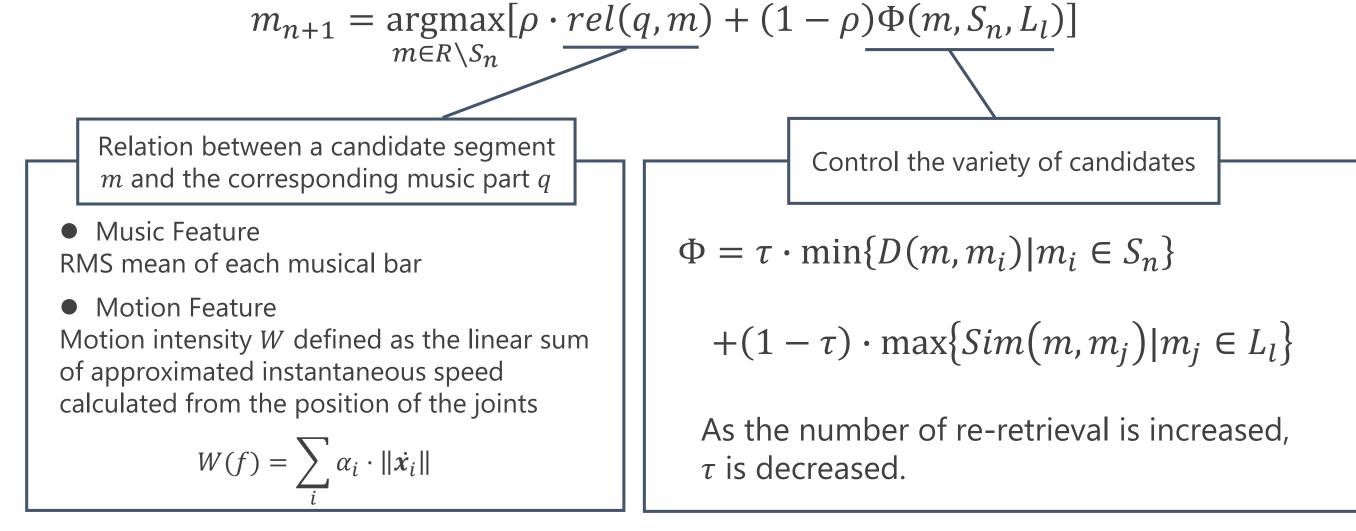
- ✓ User can see sequence candidates on a screen and simply choose preferred one.
- ✓ User can also re-retrieve motion data using relevance feedback based on the diversification framework. [Dou et al. WSDM2011]



Example of interactive sequence selection

## How are sequence candidates selected by the system?

The (n + 1)-th motion segment is given by



 $\rho$  : parameter that controls the tradeoff between rel(q,m) and  $\Phi(m,S_n,L_l)$ 

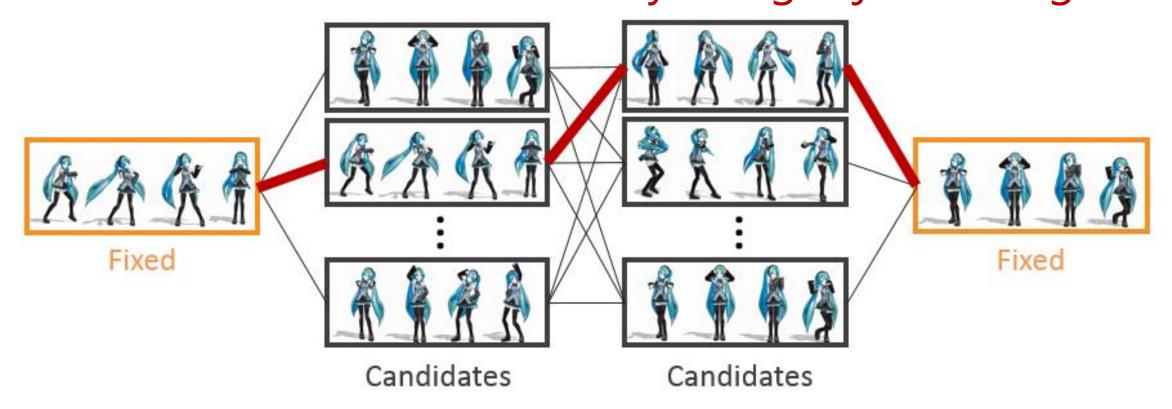
 $\alpha_i$ : regularization parameter for the *i*-th joint  $x_i$ : position of the *i*-th joint

 $S_n$ : set of motion segments already posted by the system  $L_l$ : set of motion segments the user liked  $D(m, m_i)$ : dissimilarity between m and  $m_i$  (calculated by

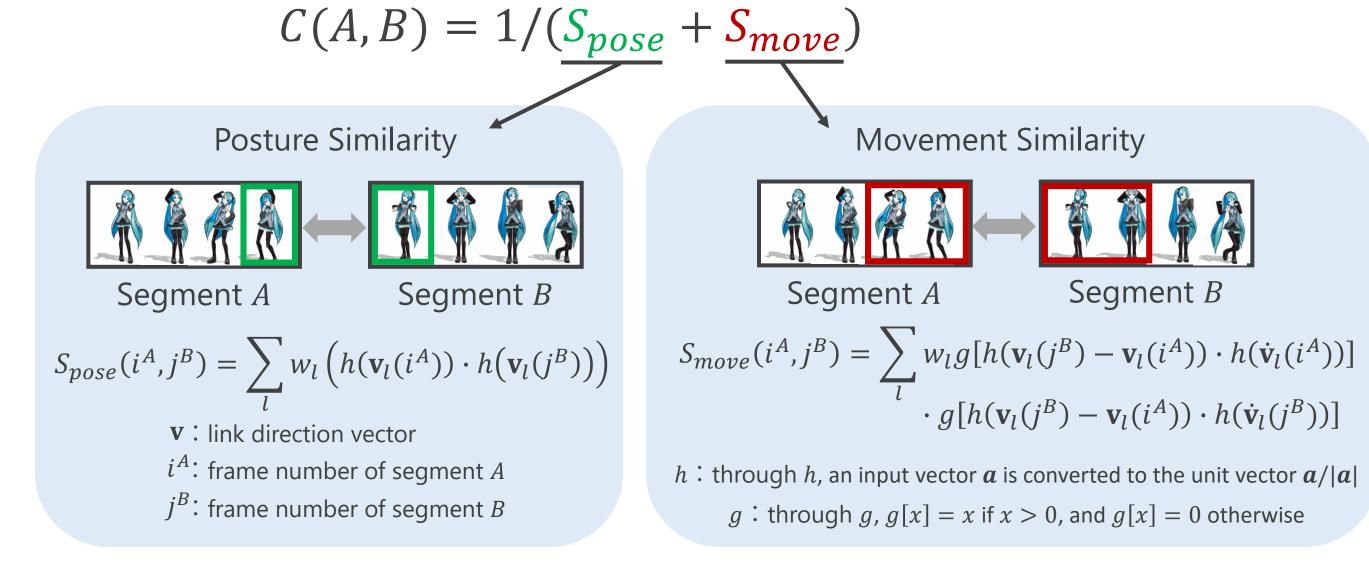
[Wang et al. 2014])  $S(m, m_j)$ : similarity between m and  $m_j$  (calculated by [Wang et al. 2014])

# Automatic Synthesis of a Dance Sequence

#### Minimization of the total costs by using Dijkstra's algorithm



- 1. The rhythm of candidate dance motion segments is synchronized to that of input music by resizing of motion segments.
- 2. The filling clips are selected by minimizing the total cost functions

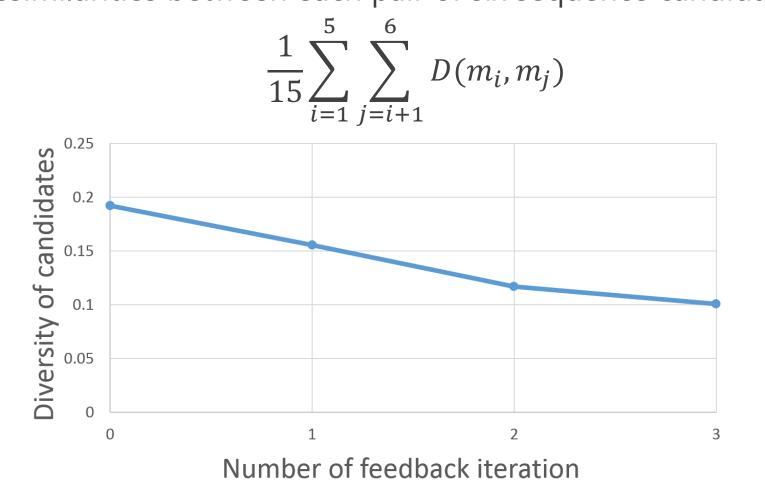


3. The resulting motion sequence is acquired by connecting the motion segment sequence using cubic interpolation.

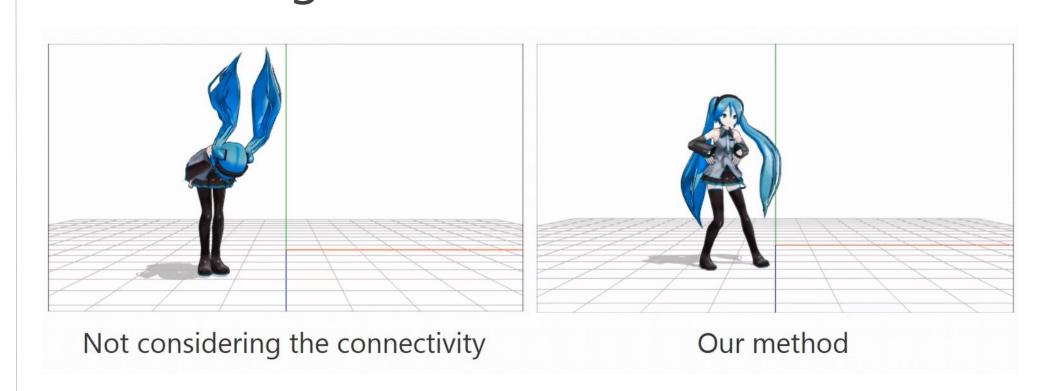
# Result and Conclusion

## Diversity of candidates

We defined the diversity of candidates as the mean of dissimilarities between each pair of six sequence candidates.



### Resulting dance animation



In the dance animation synthesized without considering the connectivity of the motion segments, character's posture rapidly changes across junctions between motion segments.

#### **♦** Conclusion

- ✓ The variety of candidates gradually converges as the number of feedback iteration is increased.
- ✓ Our system can automatically synthesize a sequence of dance by analyzing the connectivity of the motion segments.
- ✓ By this system, we can create a new dance performance for character animation reflecting a user's preference.

#### ◆ Future work

✓ A closer evaluation of usability of our system.