

ANARI: ANALytic Rendering Interface

Portable, performant access to advanced 3D rendering engines

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Motivation

The ANARI (Analytic Rendering Interface) API enables users to build the description of a scene to generate imagery, rather than specifying the details of the rendering process, providing simplified visualization application development and cross-vendor portability to diverse rendering engines, including those using state-of-the-art ray tracing.

Methodology

Visualization Engines and Applications

e.g. PARAVIEW, VTK, Visit ...



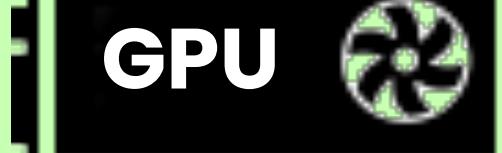
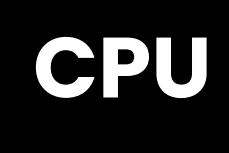
Portable Across State-of-the-Art Renderers

e.g. Intel OSPRay, Radeon ProRender, USD, NVIDIA VisRTX, OpenGL ...

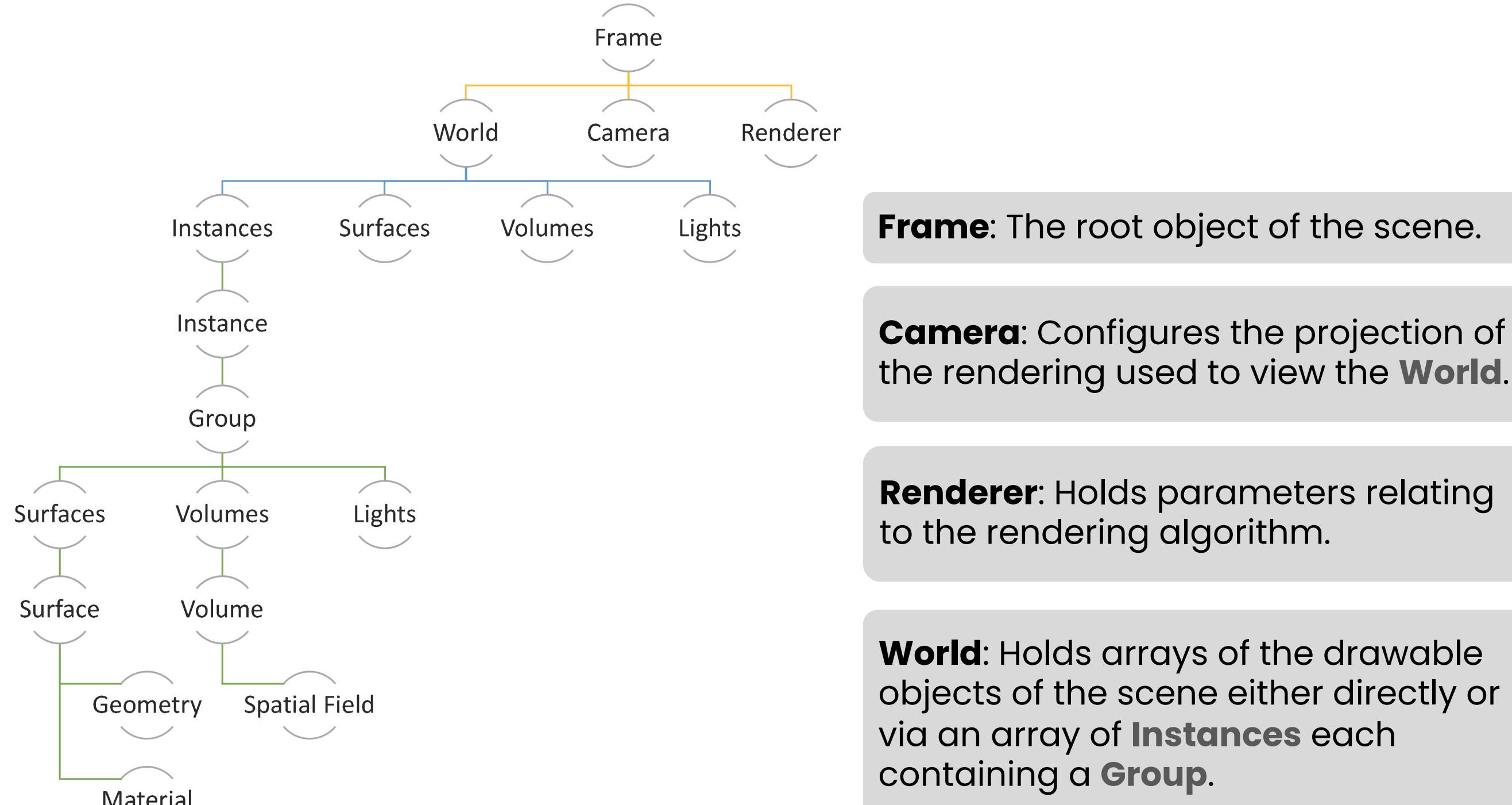
Acceleration APIs

e.g. Embree, OptiX, Radeon Rays, CUDA, OpenCL, Vulkan

Hardware



Scene Description in Memory



ANARI Rendering Results I

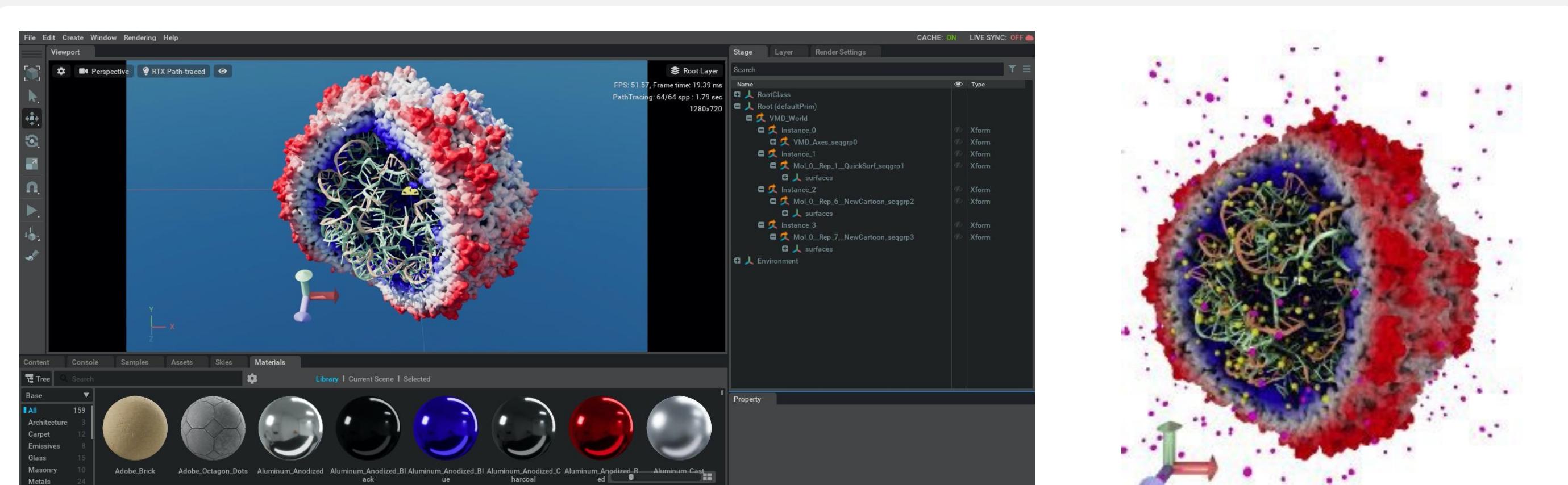


Figure 1: VMD visualization, using the Intel OSPRay ANARI device, of satellite tobacco mosaic virus capsid and its interior RNA, with surrounding solvent ions.

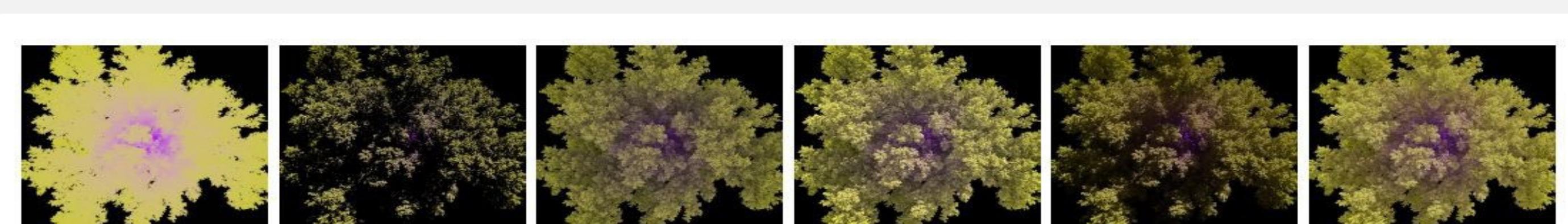


Figure 5: Comparison of lighting techniques for a complex and crowded visualization of the results of a diffusion-limited aggregation simulation, rendered using ANARI and the NVIDIA VisRTX back-end device. The lighting techniques, from left, are: raycasting of surface color, directional lighting and shadows, ambient occlusion lighting, directional lighting with ambient occlusion, directional lighting with path traced indirect lighting, and directional lighting combined with ambient occlusion and path traced indirect lighting.

Backend Loading and Initialisation

```
const char *libraryName = GetDeviceType();
m_library = anariLoadLibrary(libraryName, avtANARIDevice::StatusCallback);
m_device = anariNewDevice(m_library, "default");
if(m_device)
{
    anari::setParameter(m_device, m_device, "debug", true);
    anariCommit(m_device, m_device);

    debug5 << "[ANARI::OptiX] Done loading module and creating device" << std::endl;
    if(m_dataType == DataType::VOLUME)
        ExecuteVolume();
    else
        ExecuteSurface();
}
else
{
    std::string msg("[ANARI::OptiX] Could not load device for OptiX module.");
    EXCEPTION1(VisItException, msg);
}
```

API Calls

```
ANARIWorld avtANARIVolumeDevice::CreateWorld(ANARIDevice *device, ...)
{
    // Instances can apply transforms to groups for placement in the World
    ANARIInstance instance = anariNewInstance(*device);

    if(instance != nullptr)
    {
        ...
        // Create World
        ANARIWorld world = anariNewWorld(*device);

        // Instance
        ANARIArray1D array1D = anariNewArray1D(*device, &instance, nullptr, ANARI_INSTANCE, 1);

        anari::setAndReleaseParameter(*device, world, "instance", array1D);
        anariRelease(*device, instance);
        ...
        return world;
    }
}
```

Scene Setup and Rendering

```
ANARIFrame frame = anariNewFrame(m_device);

int screenSize[2] = {width, height};
anari::setParameter(m_device, m_frame, "size", ANARI_UINT32_VEC2, &screenSize[0]);
ANARI dataType format = ANARI_UFIXED8_RGBA_SRGB;
anari::setParameter(m_device, m_frame, "color", ANARI_DATA_TYPE, &format);
ANARI dataType depthFormat = ANARI_FLOAT32;
anari::setParameter(m_device, m_frame, "depth", ANARI_DATA_TYPE, &depthFormat);

bool t = true;
anari::setParameter(m_device, m_frame, "channelColor", ANARI_BOOL, &t);
anari::setParameter(m_device, m_frame, "channelDepth", ANARI_BOOL, &t);

anari::setParameter(m_device, m_frame, "camera", m_camera);
anari::setParameter(m_device, m_frame, "world", m_world);
anari::setParameter(m_device, m_frame, "renderer", m_renderer);
anariCommit(m_device, m_frame);

// Render frame
anariRenderFrame(m_device, m_frame);
anariFrameReady(m_device, m_frame, ANARI_WAIT);

// Map framebuffer
const void *renderedFrameBuffer = anari::map(m_device, m_frame, "color");
const void *depthBuffer = anari::map(m_device, m_frame, "depth");
```

ANARI Rendering Results II

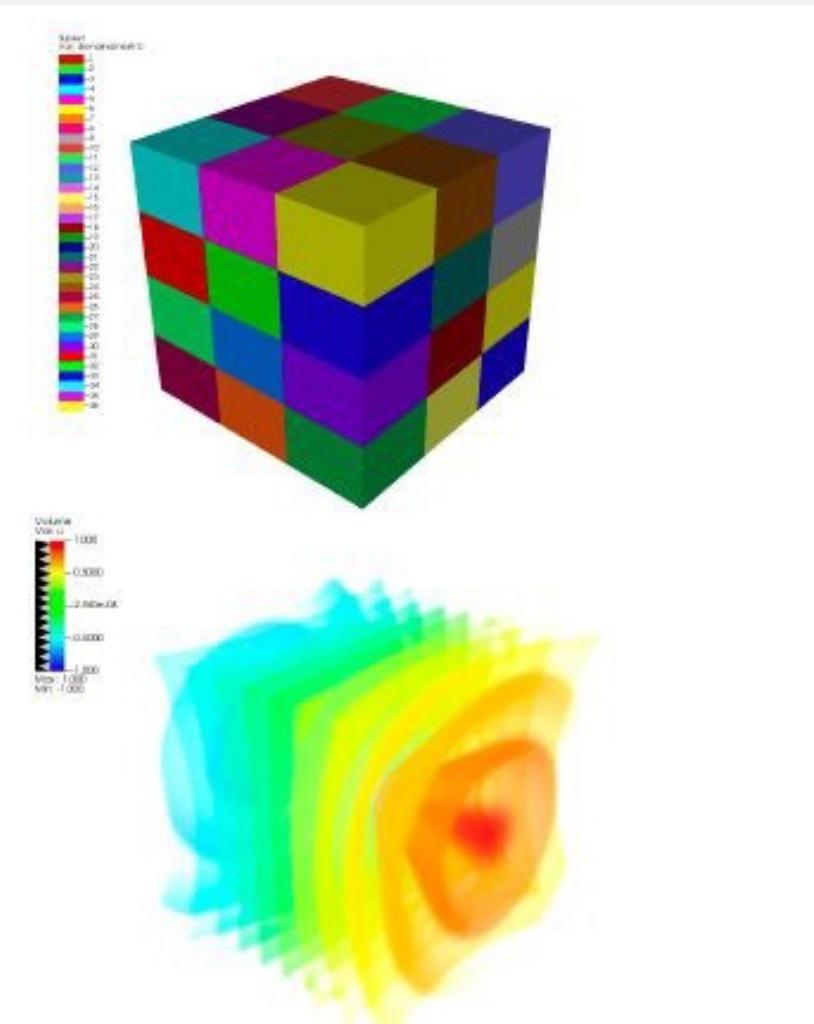


Figure 2: Visit parallel volume rendering using NVIDIA VisRTX back-end.

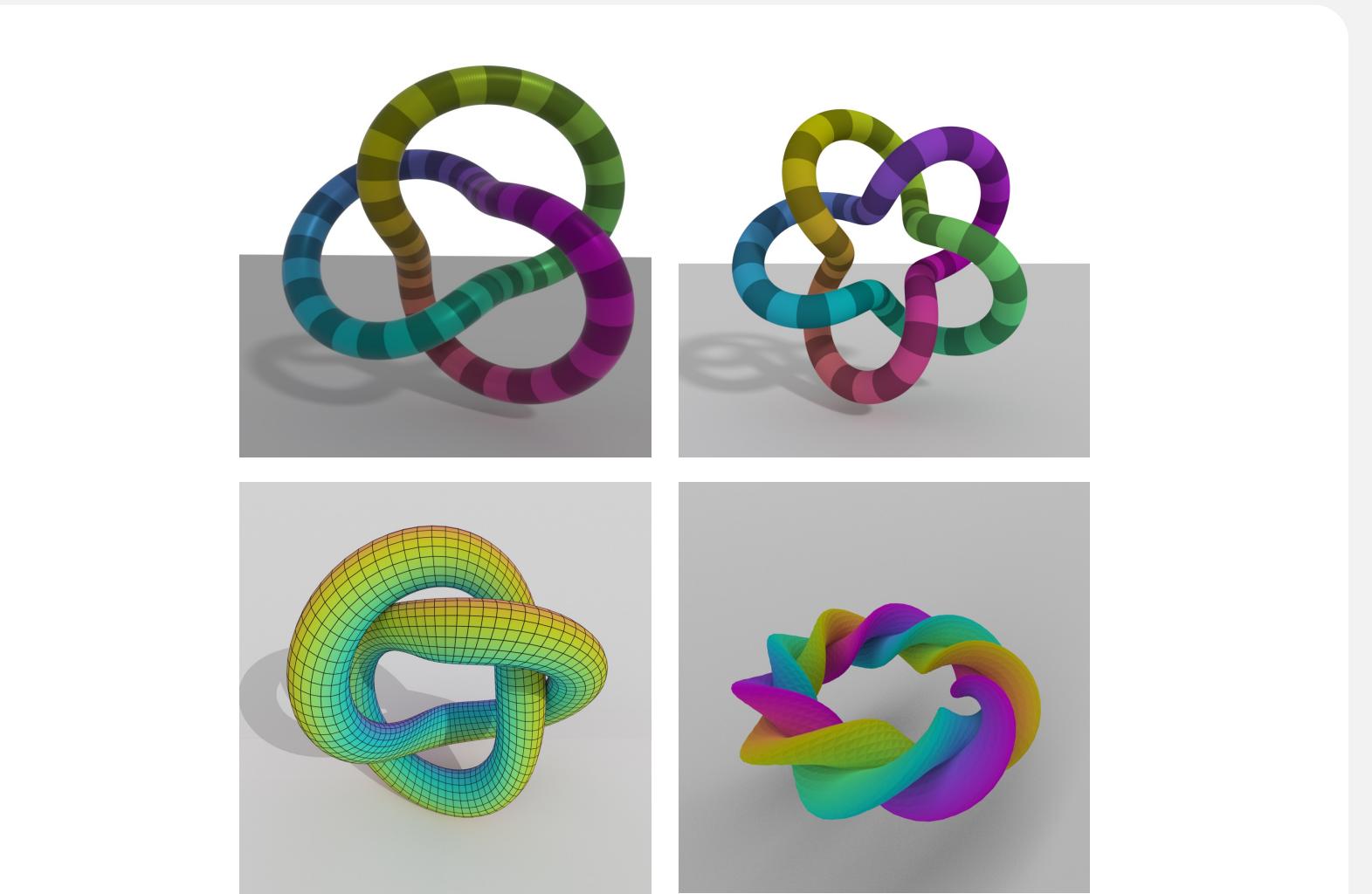


Figure 3: ANARI renderings of knots (top, Intel OSPRay) and parametric surfaces (bottom left, NVIDIA VisRTX and bottom right, AMD Radeon ProRender).

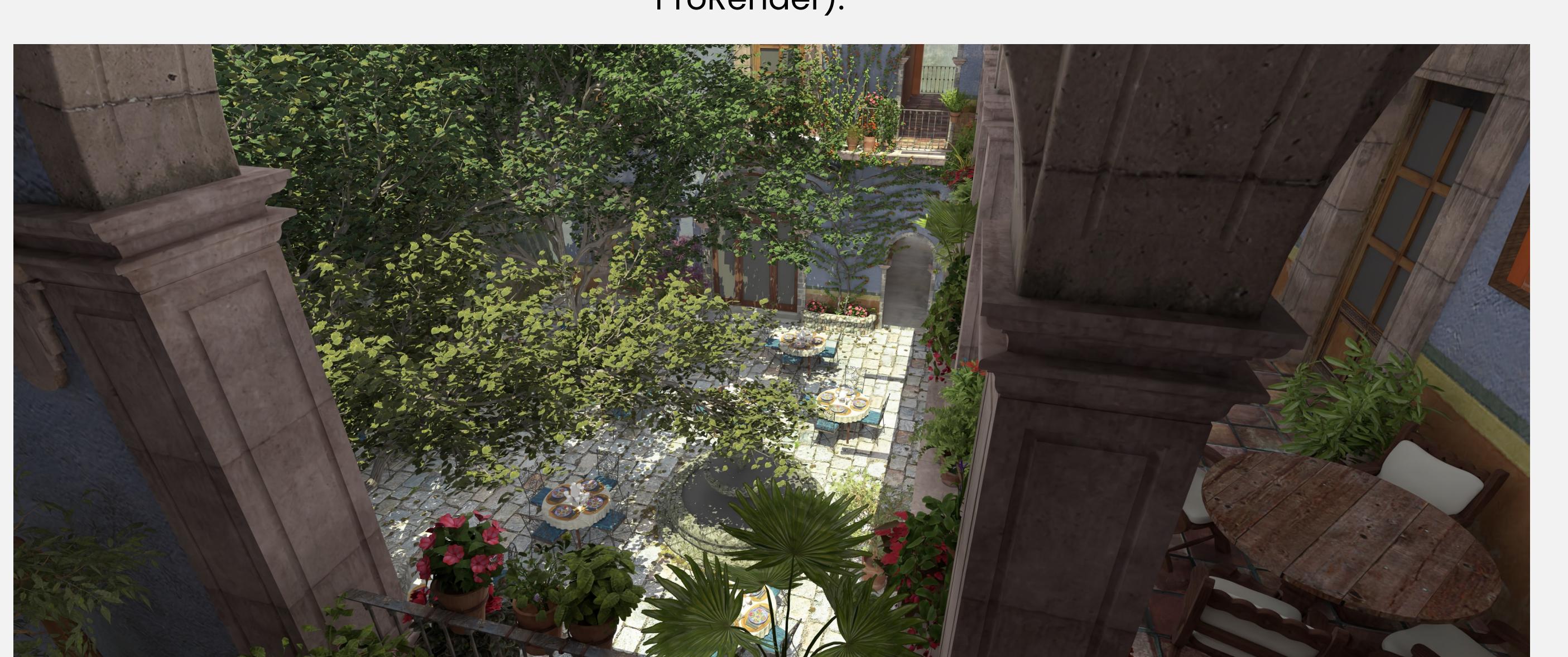


Figure 4: NVIDIA VisRTX Path traced rendering of the San Miguel scene © Guillermo M. Llaguno (<https://casual-effects.com/data>).