

Tutorial:

# Inverse Computational Spectral Geometry

Simone Melzi

Luca Cosmo


Emanuele Rodolà

Maks Ovsjanikov

Michael Bronstein



# Today's schedule

- **I** Introduction and motivations 15:00 – 15:35
- **II** Discrete spectral geometry 15:40 – 16:15
- Coffee break  16:20 – 16:40
- **III** Shape from spectrum and applications 16:40 – 17:15
- **IV** Localization and open problems 17:20 – 17:55



Tutorial:

# Inverse Computational Spectral Geometry

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# Outline

- **Motivations and Historical overview**
- **Can one hear the shape of a drum?**
- **Inverse spectral problems**
- **Teaser applications**

# Shape-from-metric

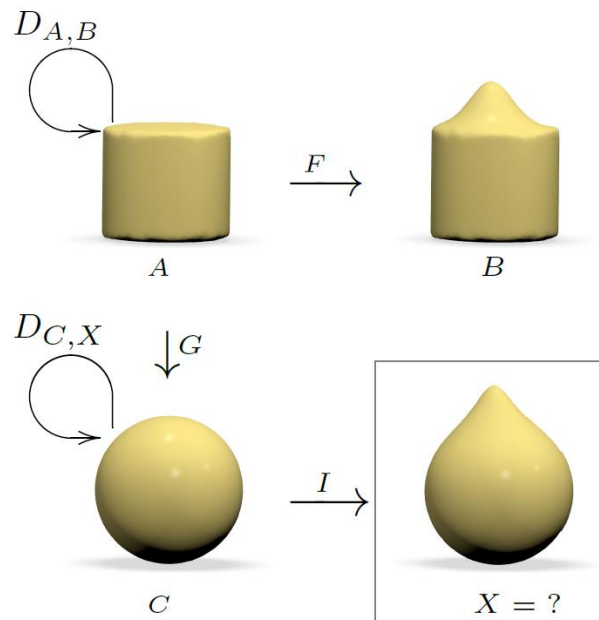


Chern et al 2018

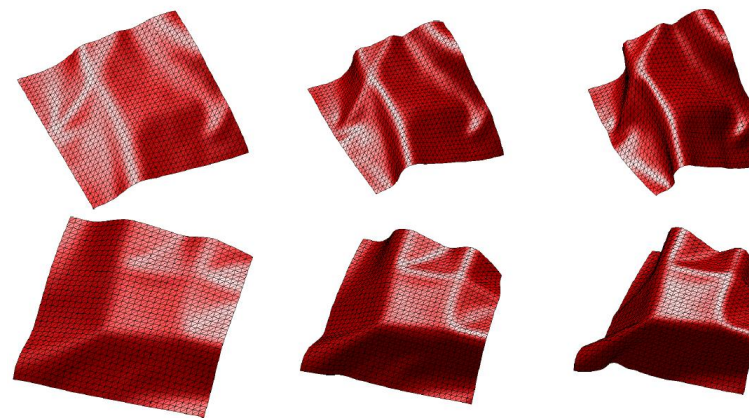


Borrelli et al 2012

# Shape-from-operator



Boscaini et al 2014



Corman et al 2017



# Wave equation



# Wave equation





# Wave equation

The wave equation for the height  $f(x, y, t)$  of the water at point  $(x, y)$  after time  $t$ :




# Wave equation

The wave equation for the height  $f(x, y, t)$  of the water at point  $(x, y)$  after time  $t$ :

$$\Delta f = -\frac{1}{c^2} \frac{\partial^2 f}{\partial t^2}$$

speed of sound  
in the fluid



First-order approximation of the motions under consideration.

# Vibrating membrane equation

The wave equation for the normal motion  $f(x, y, t)$  of a vibrating membrane («drum»):



$$\Delta f = -\frac{1}{c^2} \frac{\partial^2 f}{\partial t^2}$$

speed of sound  
in the membrane

First-order approximation of sounds in a flat object.



# Why the eigenvalue problem?

$$\Delta f = -\frac{1}{c^2} \frac{\partial^2 f}{\partial t^2}$$

To solve for  $f$ , we need only consider product functions:

$$f(x, y, t) = \phi(x, y)h(t)$$

spatial component

temporal component

# Why the eigenvalue problem?

$$\Delta f = -\frac{\partial^2 f}{\partial t^2}$$

$$f(x, y, t) = \phi(x, y)h(t)$$

Laplacian eigenfunction

oscillating functions  
with frequency  $\lambda$

$$\Delta \phi h = -\frac{\partial^2 \phi h}{\partial t^2}$$

$$\frac{\Delta \phi}{\phi} = -\frac{h''}{h}$$

$$\lambda = \lambda$$

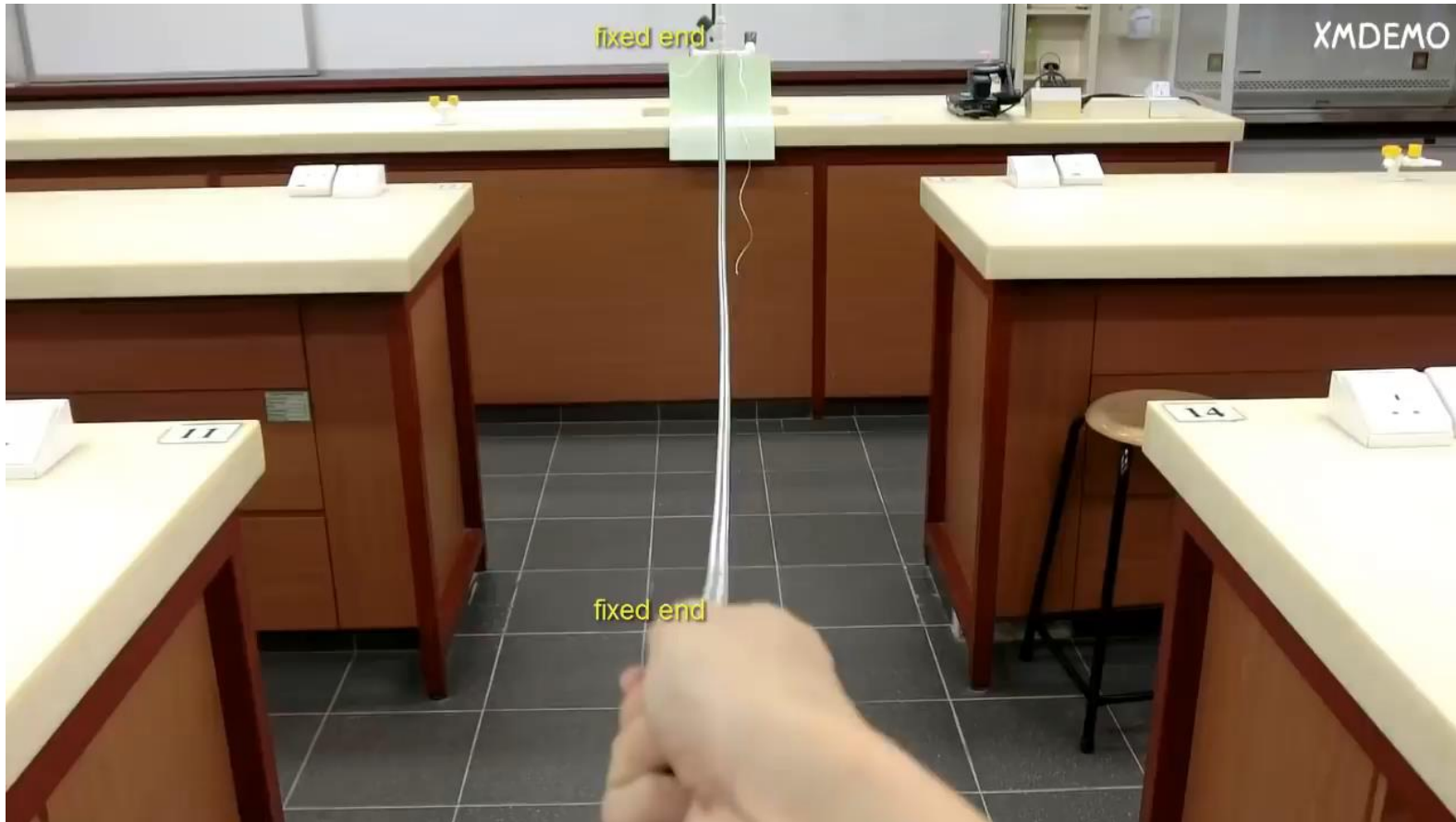
$$-\frac{h''}{h} = \lambda$$

$$h(t) = e^{it\sqrt{\lambda}}$$

$$\Delta \phi = \lambda \phi$$

# Stationary waves

Physically, the product motions  $f(x, y, t) = \phi(x, y)h(t)$  are **stationary**.



Video: Chua Kah Hean, 2016

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# Whispering galleries

Behavior is not always easy to grasp even on simple domains.

Example:

On the disk, there is high concentration along the boundary («whispering gallery effect»)

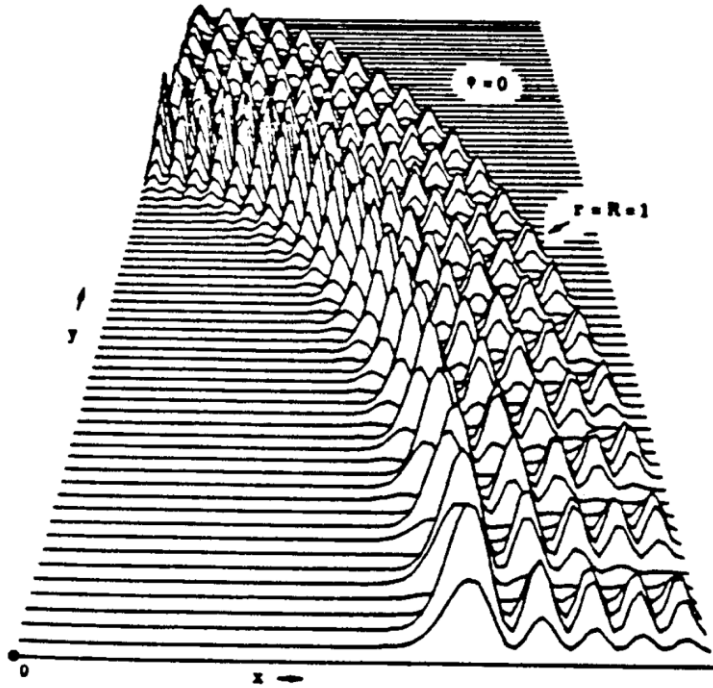


Figure: Sarnak, 1995



Voltone del Podestà, Bologna (Italy)

# Computing eigenvalues

$$\Delta\phi_i = \lambda_i\phi_i$$

Very few examples where the spectrum can be determined explicitly.



«As a shocking example of our ignorance, we know nothing about regular hexagons, not even the first eigenvalue.»

[Marcel Berger, 2002]

Our drums



# Direct and inverse problems

Given the (approximate) **shape** of a domain  $D$ ,  
what can I deduce about its **spectrum**?  
(spectral geometry so far)

Given the (approximate) **spectrum** of a domain  $D$ ,  
what can I deduce about its **shape**?  
(this tutorial)

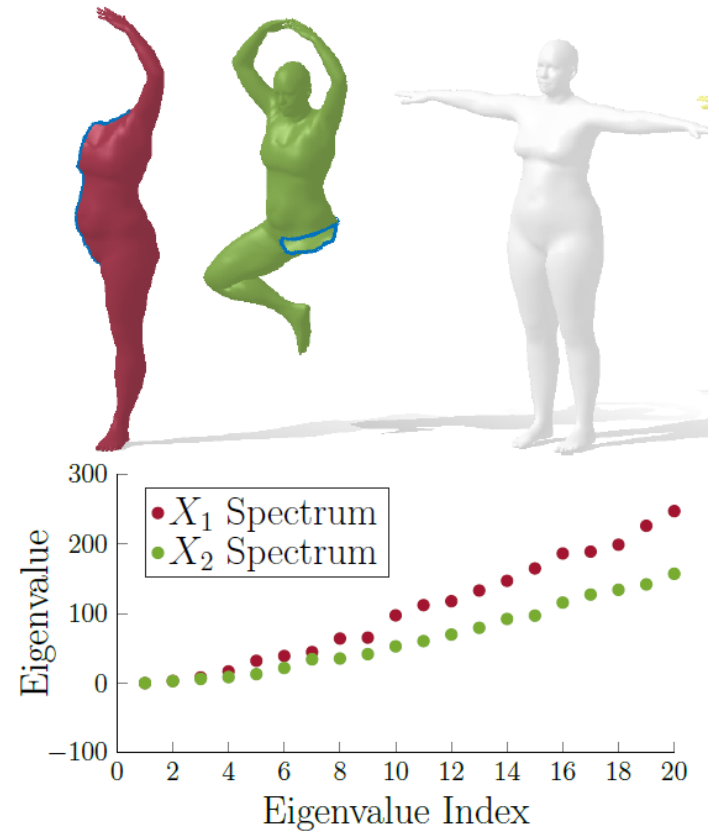
# Direct problems

- Asymptotic expansion of the counting function:

$$N(\lambda) = \# \{ \lambda_i \leq \lambda \}$$

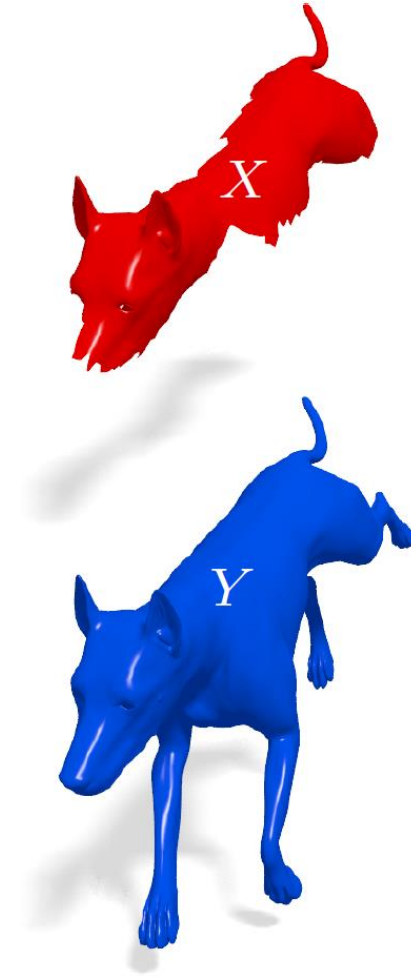
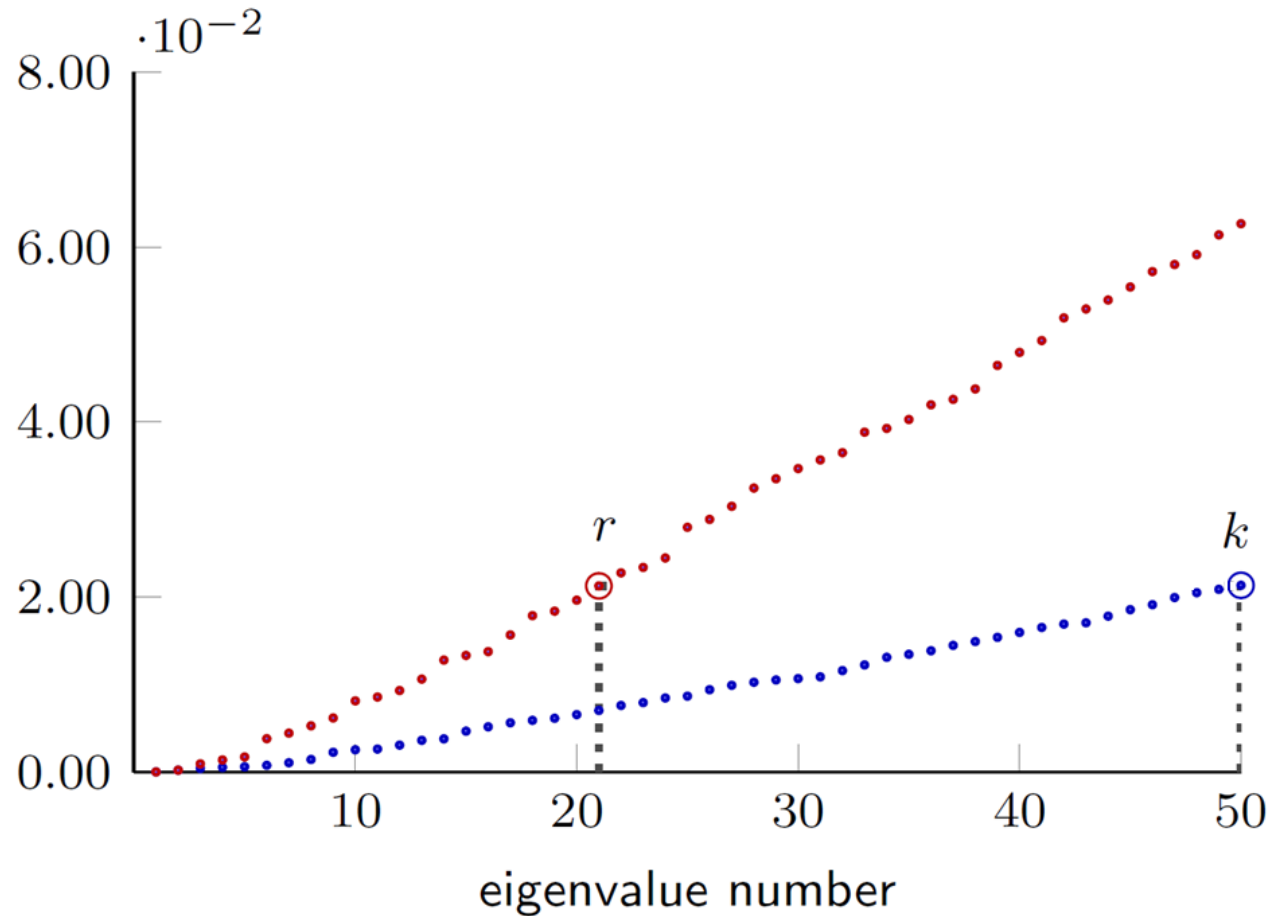
- Tight estimates of  $\lambda_1$

- Relation between eigenvalues of  $D$  and those of a sub-domain  $P \subset D$



[Moschella et al 2021]

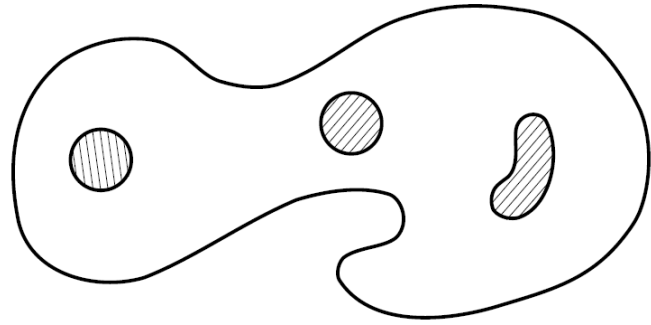
# Inverse problems



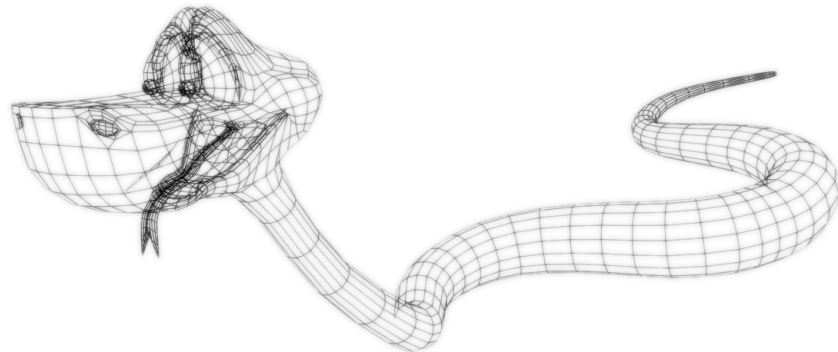
- Compute the area, perimeter, and number of holes in a shape from its eigenvalues.

# Inverse problems

- Compute the area, perimeter, and number of holes in a shape from its eigenvalues.



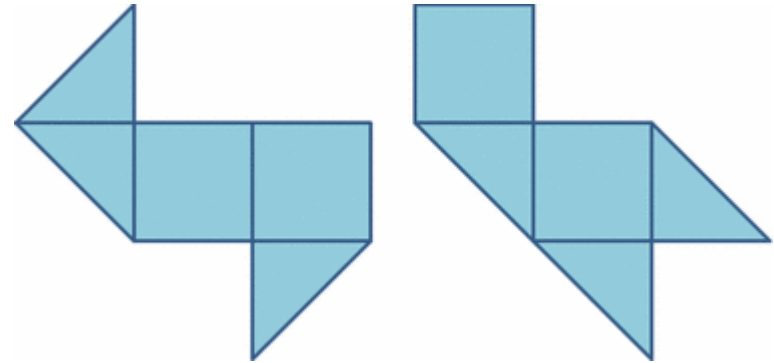
- Recover a 3D shape from its eigenvalues ~~and eigenfunctions.~~



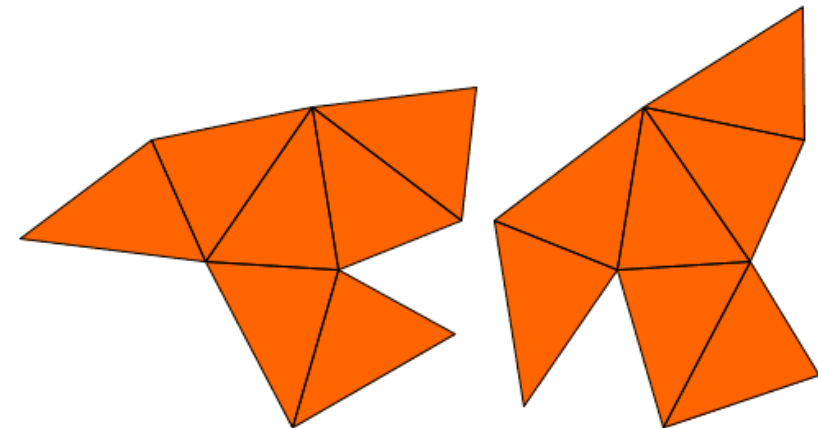
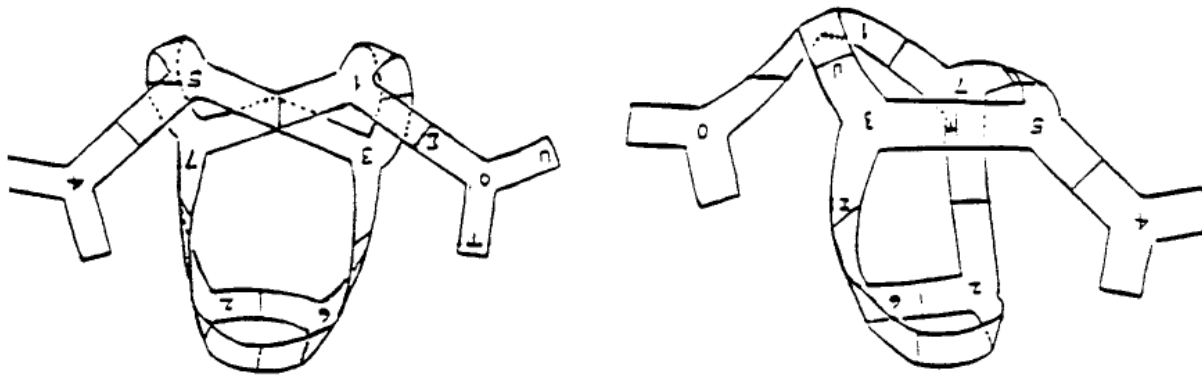
# Isospectral domains

Are eigenvalues enough?

- Conjecture: yes! [Gel'fand, 1962]
- Counterexample: no! [Milnor, 1964; Gordon et al, 1992]



Except for notable exceptions (disks, spheres), in general, shapes are not fully characterized by their spectrum.



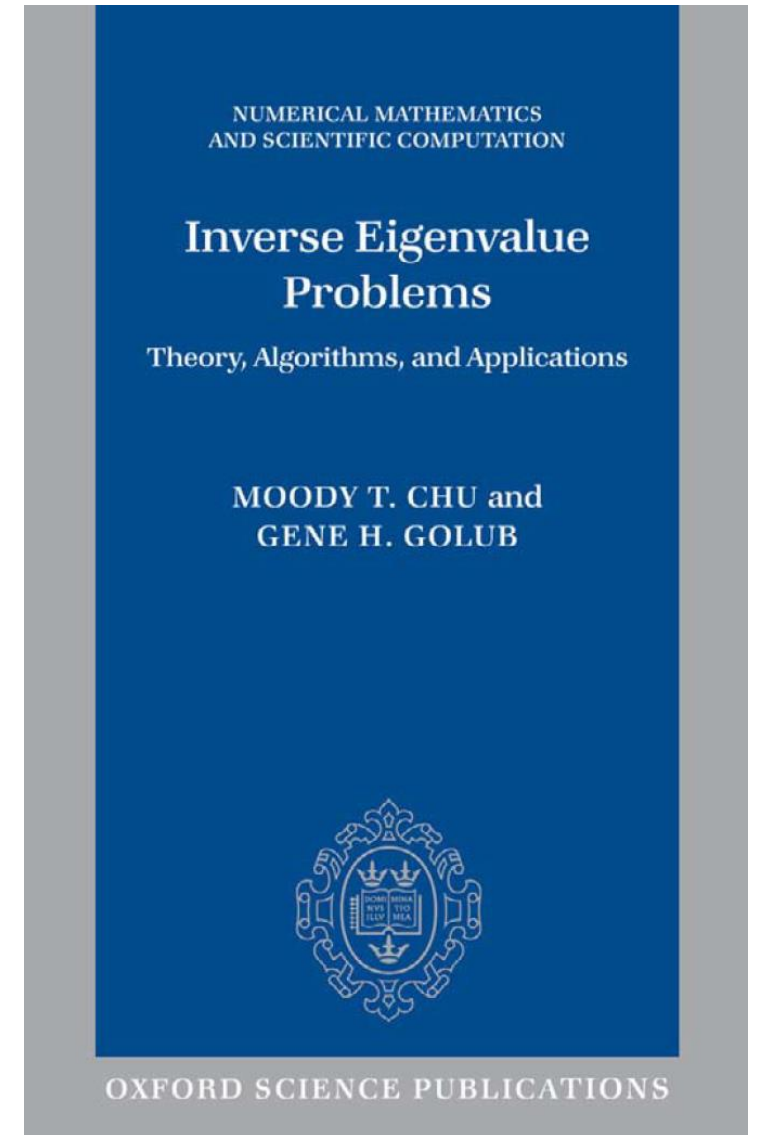


# Matrix analysis

The problem has also been tackled from a purely **linear-algebraic** perspective.

These approaches assume:

- Knowledge of the matrix structure
- Partial knowledge of the eigenvectors
- Partial knowledge of the matrix entries



# Matrix analysis

In 2019, Terry Tao and colleagues rediscovered a little-known result from Löwner (1934).

## Eigenvectors from eigenvalues

13 August, 2019 in [math.RA](#), [paper](#) | Tags: [eigenvalues](#), [eigenvectors](#), [Peter Denton](#), [Stephen Parke](#), [Xining Zhang](#)

[Peter Denton](#), [Stephen Parke](#), [Xining Zhang](#), and I have just uploaded to the arXiv the short unpublished note "[Eigenvectors from eigenvalues](#)". This note gives two proofs of a general eigenvector identity observed recently [by Denton, Parke and Zhang](#) in the course of some quantum mechanical calculations. The identity is as follows:

**Theorem 1** Let  $A$  be an  $n \times n$  Hermitian matrix, with eigenvalues  $\lambda_1(A), \dots, \lambda_n(A)$ . Let  $v_i$  be a unit eigenvector corresponding to the eigenvalue  $\lambda_i(A)$ , and let  $v_{i,j}$  be the  $j^{\text{th}}$  component of  $v_i$ . Then

$$|v_{i,j}|^2 \prod_{k=1; k \neq i}^n (\lambda_i(A) - \lambda_k(A)) = \prod_{k=1}^{n-1} (\lambda_i(A) - \lambda_k(M_j))$$

where  $M_j$  is the  $(n-1) \times (n-1)$  Hermitian matrix formed by deleting the  $j^{\text{th}}$  row and column from  $A$ .

# Can it still be useful in practice?

Mathematically, the problem is beyond reach today.

Yet, in the Middle Ages, bell makers detected invisible cracks by tolling the bell.



Antonio Delli Quadri, whose family is in the bell-making business since the 14<sup>th</sup> century

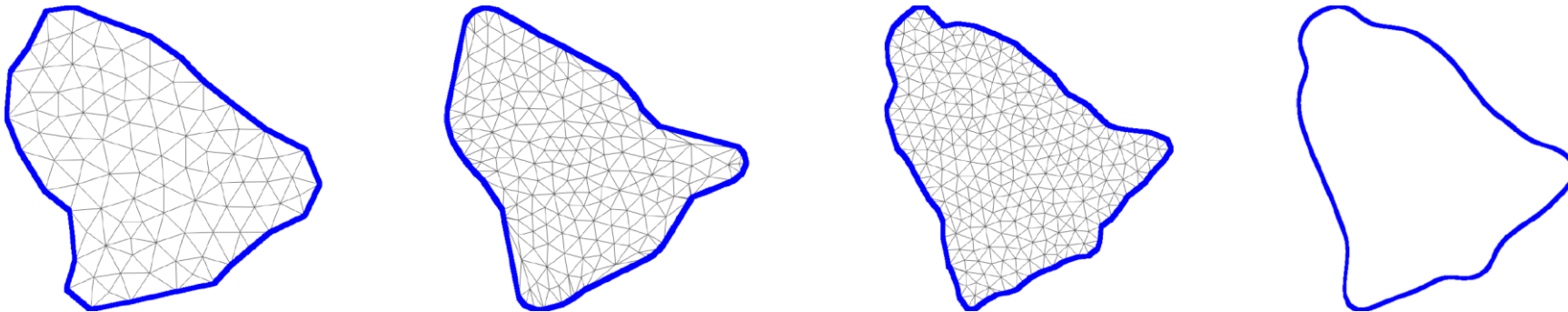
“This is a complex trade that involves precise understanding of mathematics, physics, **geometry** and music”



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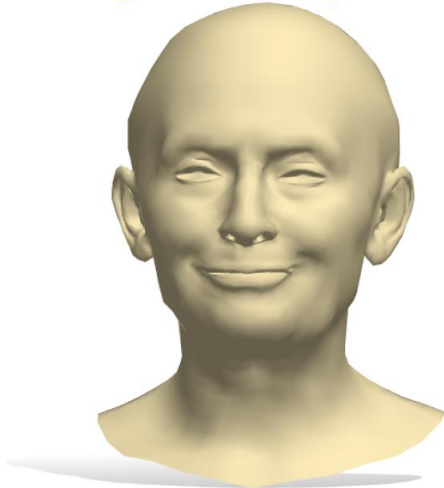


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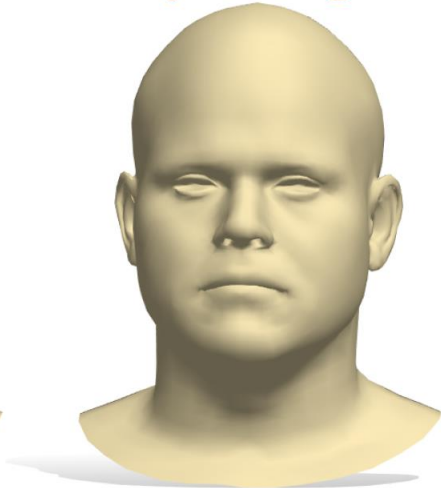
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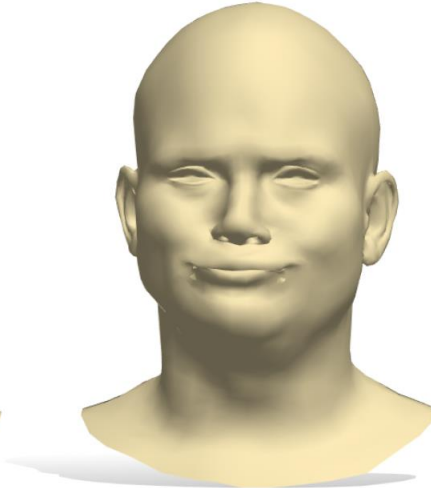
pose target



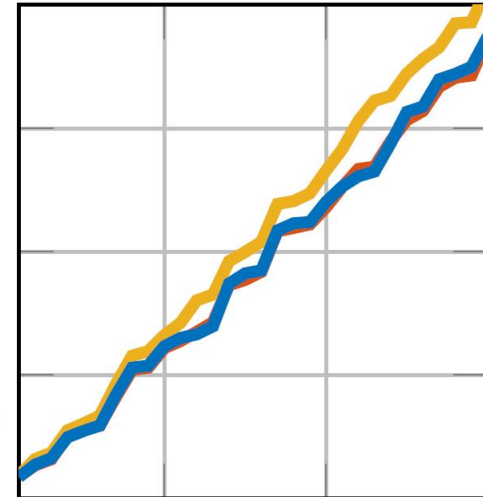
style target



our result



eigenvalues



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