

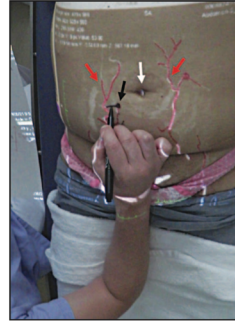
A Projection Mapping System onto a Human Body for Medical Applications

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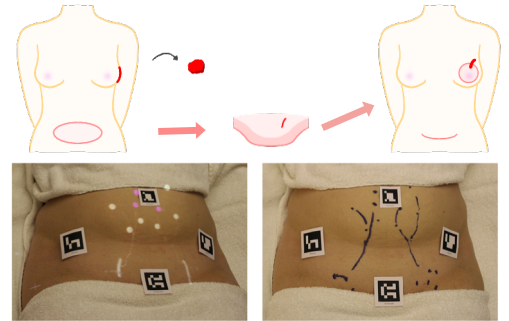
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1. Introduction

- Abdominal free flap breast reconstruction
→ require **identifying and locating the blood vessels**
- Related work
→ need four markers
→ position shifting problem
- The proposed method
→ **without any markers**
→ **solve the position shifting problem**



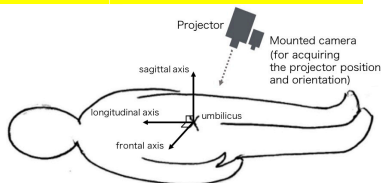
[Sostuka 2014]



[Hummelink 2016]

2. The proposed system

Camera-Projector system

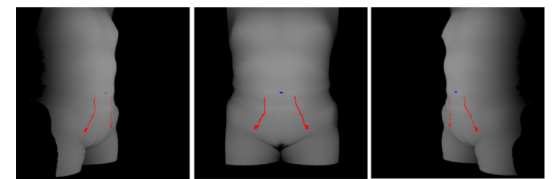
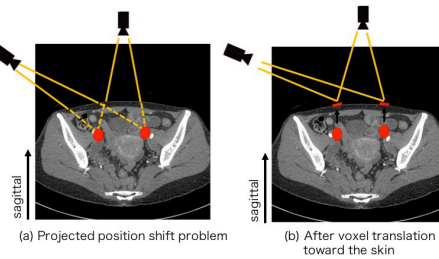
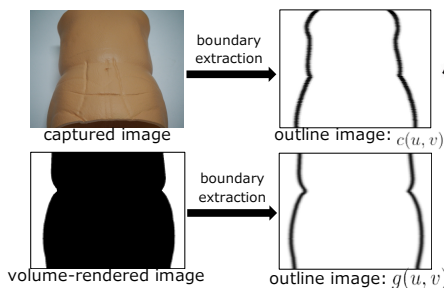


Estimation of the camera position and orientation

- match **the outlines of the body and a volume-rendered image**
- use **the umbilicus position** to reduce the number of parameters determining the camera position and orientation
- **optimization problem**

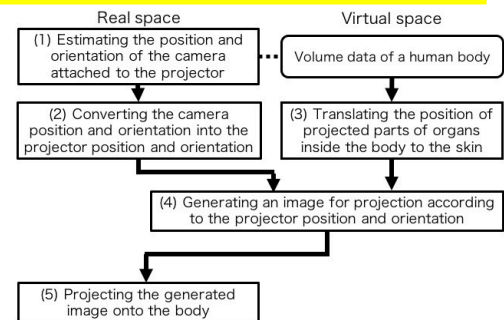
$$\text{minimize } \frac{1}{N_w N_h} \sum_{v=0}^{N_h-1} \sum_{u=0}^{N_w-1} (c(u, v) - g(u, v))^4$$

$c(u, v)$, $g(u, v)$: intensities of outline images in a captured and a volume-rendered images



Projection invariant to the pose of the projector

Process flow of the proposed method

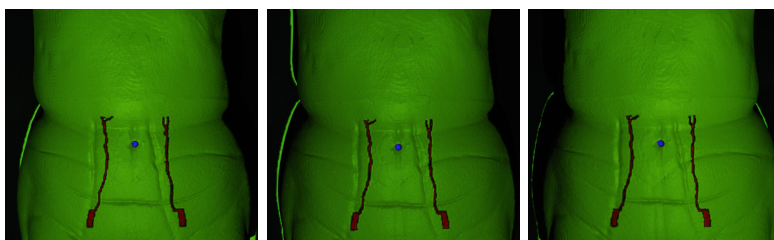


Translation of blood vessel voxels to the skin

- solve the position shifting problem
- the view of the doctor is the sagittal direction in surgery
- the blood vessels are always projected at **the predefined position** where they are observed from the sagittal axis.

3. Experiments

- Projection mapping onto an abdominal model from three different directions
- The blood vessels are always projected at the same position on the model
- The IoU of two regions: the skin and the projected skin
→ IoU: (a) 96.3%, (b) 95.7%, (c) 91.2%



green:
the projected skin
red:
the blood vessels
blue:
the umbilicus

Experimental setting



The proposed system:
an open platform camera (OLYMPUS AIR A01) and a LED portable projector (AddTron Technology QUMI Q6)