



Erratum: Adjustable Constrained Soft-Tissue Dynamics

A conflict of interest statement was mistakenly omitted from the article by Wang et al. [WZB20]. The statement is provided here:

The jellyphant mesh and its geometric proxy motion was obtained at Ziva Dynamics. Jernej Barbic is a shareholder, CTO and board member of Ziva Dynamics. Ziva Dynamics was not involved in this research. Nothing in this paper is to be understood as endorsement of Ziva Dynamics or its products.

Reference

[WZB20] WANG B., ZHENG M., BARBIČ, J.: Adjustable Constrained Soft-Tissue Dynamics. *Computer Graphics Forum* 39, 7 (2020), 69–79.