



**Figure 12: Mesh reconstruction.** (a) A sampled 3D point cloud with surface normals. Surface reconstruction using (b) alpha shapes, (c) template deformation, and (d) Poisson surface reconstruction. (e) Surface reconstruction detail for (top left) point samples, (top right) alpha shapes, (bottom left) template deformation and (bottom right) Poisson surface reconstruction.

significant issue is that the notion of one-to-one point correspondences for objects in diverse datasets such as chairs is ill-founded. The result is that the input data for our method can feature poor correspondences, which has a knock-on effect on sample quality. We believe that a promising avenue for future research is to represent objects using unordered point sets, which would enable the use of large datasets without pre-processing, and correspondence quality issues. Some work has already taken place in this area, with deep learning methods applied to 3D point sets for the purpose of object classification, semantic scene parsing and part segmentation [QSMG16]. We believe there is potential to modify these methods for generative modelling, which would enable the synthesis of arbitrary point clouds.

Although the ShapeVAE’s samples display a good range of variability, they are somewhat lacking in fine detail in comparison with the input point sets. This is an issue that has been documented in the machine learning literature, in which VAE-based generative models of images demonstrate blurriness and a lack of detail [DB16]. This effect has been attributed to the use of unimodal generative distributions such as Gaussians. One solution to this issue that has emerged in generative models is the use of generative adversarial networks (GANs), which demonstrate mode-seeking behaviour, and thus produce samples closer to the true data manifold than alternative approaches. As such, a potential future direction is to make use of GAN with a similar architecture to the ShapeVAE decoder to generate objects.

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